# **Empowering You with Advanced Autonomy Solutions**



Open Modular Environment for General Autonomy

## **Open Modular Architecture**

Adapt OMEGA to suit your unique needs and applications. With its interchangeable components and expandable functionalities, customization has never been easier.

# **Unbeatable Connectivity**

Stay connected and in control with the optional Rajant Mesh network integration. OMEGA ensures reliable and seamless communication, enabling mission-critical operations in even the most challenging environments.

## **Open Software Architecture**

OMEGA's open architecture enables advanced navigation applications for precise and autonomous flight, allowing you to focus on your objective.

## **Powerful Compute Module**

OMEGA incorporates industry-leading embedded compute platforms, delivering exceptional processing power and computing capabilities.

## **Superior Sensor**

OMEGA is equipped with cutting-edge Ouster OS Lidar technology, providing precise and comprehensive environment perception. Experience enhanced situational awareness and obstacle avoidance for safe and efficient autonomous flights.







## **SYSTEM SPECIFICATIONS**

Unlock the limitless possibilities of open autonomy with OMEGA by UVify. With its state-of-the-art open modular design, advanced technology, and intelligent navigation capabilities, OMEGA gives you the power to take autonomous drone technology to new heights. OMEGA empowers you to redefine what's possible. Contact UVify today to learn more about OMEGA and how it can transform your operations. Discover the power of open autonomy with OMEGA. Unlock endless possibilities and redefine what's possible with OMEGA.

#### **PLATFORM**

| Dimensions (LxWxH)        | 419 x 449 x 253 mm                                 |
|---------------------------|--|
| Weight (battery excluded) | 2,850 g  |
| Operating frequency       | 2.4 GHz, 5.8 GHz<br>(Channel will vary by country) |
|                           | Sub 1 GHz<br>(Country-specific frequency)          |
| Hovering accuracy         | ±0.1 (with SLAM or RTK)                            |
| Max horizontal speed      | 10 m/s   |
| Max ascent speed          | 6 m/s  |
| Max descent speed         | 5 m/s  |

#### **BATTERY**

| Capacity                    | 10,000 mAh  |
|-----------------------------|-------------|
| Voltage                     | 22.2 V      |
| Battery type                | Li-lon 6S   |
| Net weight                  | 900 g       |
| Operating temperature       | 0° to 50°C  |
| Optimal storage temperature | 22° to 30°C |

#### **GNSS (RTK)**

| Receiver type             | 184-channel u-blox F9 engine<br>GPS L1C/A L2C, GLO L1OF<br>L2OF, GAL E1B/C E5b, BDS B1I<br>B2I, QZSS L1C/A L1S L2C, SBAS<br>L1C/A |
|---------------------------|---|
| Position accuracy         | (RTK) 0.01 m + 1 ppm CEP  |
| GNSS                      | GPS + QZSS / SBAS, GLONASS,<br>Galileo, Beidou  |
| Number of concurrent GNSS | 4   |
| Moving baseline RTK       | Supported   |

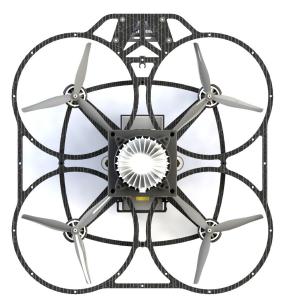
## **Payload Options**

| Companion computer | Jetson Orin NX  |
|--------------------|---|
|                    | Intel NUC   |
| Cameras            | Intel D435, D435i, D455<br>D435f, D435if, MIPI, Luxonis |
| Sensors            | Ouster OS0-32/64/128                                    |

#### **SOFTWARE**

| Flight control     | PX4 (UVify Core)  |
|--------------------|---|
|                    | Ardupilot   |
| High-level control | ROS Melodic (Jetson)<br>ROS Noetic (Intel)<br>MATLAB UAV Toolbox (Both) |
|                    |   |

#### **TOP VIEW**



#### **SIDE VIEW**



## **SALES CONTACT**

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